

**GEOMETRY TMS EXAM**  
February 17, 2016

**Duration:** 3 hours.

(1) Show that  $N = \{[x : y : z : w] \in \mathbb{R}P^3 \mid x^3 + y^3 + z^3 + w^3 = 0\}$  is an embedded submanifold of  $\mathbb{R}P^3$ , real projective space of dimension 3, and compute its dimension.

(2) Let  $M$  be an orientable smooth manifold and fix an orientation for unit circle  $S^1$ . Given a smooth map  $\gamma : S^1 \rightarrow M$  and a differential 1-form  $\alpha \in \Omega^1(M)$  define  $\int_\gamma \alpha := \int_{S^1} \gamma^*(\alpha)$ .

a) Show that if  $\alpha$  is exact then for any  $\gamma : S^1 \rightarrow M$ ,

$$\int_\gamma \alpha = 0.$$

b) Show that if  $d\alpha = 0$ , and  $H : [0, 1] \times S^1 \rightarrow M$  is a smooth map then,

$$\int_{\gamma_0} \alpha = \int_{\gamma_1} \alpha,$$

where  $\gamma_0(\theta) = H(0, \theta)$  and  $\gamma_1(\theta) = H(1, \theta)$ .

(3) Let  $O(n)$  denotes the orthogonal  $n \times n$  real matrices and  $M(n)$  denotes  $n \times n$  real matrices.

a) Show that the tangent space of  $O(n)$  at the identity matrix,  $T_I O(n)$  is the space of all anti-symmetric matrices.

b) Show that for any  $A \in O(n)$ ,  $T_A O(n) = \{XA \mid X^T = -X\}$ .

c) Show that if  $X \in T_I O(n)$  then  $e^X \in O(n)$  where  $e^X = I + X + \frac{1}{2}X^2 + \frac{1}{3!}X^3 + \dots$ .

d) Consider the smooth map  $\exp : M(n) \rightarrow M(n)$ , defined as  $\exp(X) = e^X$ . Show that the differential  $d\exp(0)$  at zero matrix  $0 \in M(n)$  is the identity linear transformation.

(4) Let  $Z$  be the preimage of a regular value  $y \in Y$  under the smooth map  $F : X \rightarrow Y$  between smooth manifolds  $X$  and  $Y$ . Prove that the kernel of the derivative  $dF_x : T_x X \rightarrow T_y Y$  at any point  $x \in Z$  is precisely the tangent space to  $Z$  at  $x$ ,  $T_x Z$ .

(5) Define  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  by  $F(u, v) = (u, v, u^2 - v^2)$ . On  $\mathbb{R}^2$  with coordinates  $(u, v)$  consider the following vector fields;  $U_1 = u \frac{\partial}{\partial v} - v \frac{\partial}{\partial u}$  and  $U_2 = u \frac{\partial}{\partial u}$  and on  $\mathbb{R}^3$  with coordinates  $(x, y, z)$  consider 2-form  $\omega = ydx \wedge dz + xdy \wedge dz$  and 1-form  $\eta = zdx + xdy + ydz$ . Compute the following:

a)  $F_*[U_1, U_2]$

b)  $d\omega$

c)  $F^*(d\eta)$

d)  $F^*(\omega)(p)[V_1, V_2]$  where  $V_1 = (1, 2)$  and  $V_2 = (0, 1)$  are the vectors in  $T_p \mathbb{R}^2$ , for  $p = (1, 1) \in \mathbb{R}^2$

e)  $\omega_{F(p)}(X_1, X_2)$  where  $X_1 = F_*(V_1)$  and  $X_2 = F_*(V_2)$ .