## Graduate Preliminary Examination Differentiable Manifolds Duration: 3 hours

September 26, 2003

1. We identify  $\mathbb{R}^4$  with the set of  $2 \times 2$  real matrices.

(5 pts.) (a) Show that the set  $SL(2,\mathbb{R})$  of  $2 \times 2$  real matrices whose determinant is equal to 1 is a submanifold of  $\mathbb{R}^4$ . What is its dimension?

(5 pts.) (b) Prove that the tangent space to  $SL(2, \mathbb{R})$  at the identity matrix  $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ , may be identified with the set of matrices of zero trace.

**2.** (3 pts.) (a) Show that the 1-form  $\omega = \frac{xdy - ydx}{x^2 + y^2}$  defined on  $\mathbb{R}^2 - \{(0,0)\}$  is closed.

(3 pts.) (b) Calculate the integral  $\int_{S^1} \omega$ , where  $S^1$  is the unit circle in  $\mathbb{R}^2$ .

(4 pts.) (c) Let  $\Sigma$  be the smooth surface shown below with boundary C. Prove that there is no smooth map  $\phi : \Sigma \to S^1$  such that  $\phi_{|C} : C \to S^1$ , the restriction of  $\phi$  to the boundary C, is a diffeomorphism.

**3.** Let  $f: X \to Y$  is a smooth map between manifolds,  $f^*$  is the induced map between the algebras of differential forms of X and Y and d is the exterior derivative.

(5 pts.) (a) Prove that  $d \circ f^* = f^* \circ d$ .

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(5 pts.) (b) If  $X = \partial W$  for some compact smooth manifold W, and  $\omega$  is a closed *n*-form on Y with  $n = \dim X$ , then show that

$$\int_X f^*(\omega) = 0.$$

**4.** (10 pts.) A curve in a manifold X is a smooth map  $t \mapsto c(t)$  of an interval of  $\mathbb{R}^1$  into X. The velocity vector of the curve c at time  $t_0$  - denoted simply by  $\frac{dc}{dt}(t_0)$  is defined to be the vector  $dc_{t_0}(1) \in T_{x_0}X$ , where  $x_0 = c(t_0)$  and  $dc_{t_0} : \mathbb{R}^1 \to T_{x_0}X$  is the differential of c at  $t_0$ . In case  $X = \mathbb{R}^k$  and  $c(t) = (c_1(t), \cdots, c_k(t))$  in coordinates, check that

$$\frac{dc}{dt}(t_0) = (c'_1(t), \cdots, c'_k(t)).$$

Prove that any vector in  $T_x X$  is the velocity vector of some curve in X, and conversely.